

Solutions:

1.a) Since $\alpha(t) = (e^t \cos t, e^t \sin t, e^t)$ then we have,

$$\alpha'(t) = e^t(\cos t, \sin t, 1) + e^t(-\sin t, \cos t, 0) = e^t(\cos t - \sin t, \sin t + \cos t, 1),$$

$$\begin{aligned}\alpha''(t) &= e^t(\cos t - \sin t, \sin t + \cos t, 1) + e^t(-\sin t - \cos t, \cos t - \sin t, 0) \\ &= e^t(-2\sin t, 2\cos t, 1),\end{aligned}$$

$$\begin{aligned}\alpha'''(t) &= e^t(-2\sin t, 2\cos t, 1) + e^t(-2\cos t, -2\sin t, 0) \\ &= e^t(-2\sin t - 2\cos t, 2\cos t - 2\sin t, 1),\end{aligned}$$

$$\|\alpha'(t)\| = e^t \sqrt{(\cos t - \sin t)^2 + (\sin t + \cos t)^2 + 1} = e^t \sqrt{3},$$

$$\begin{aligned}\alpha'(t) \times \alpha''(t) &= e^{2t} \begin{vmatrix} U_1 & U_2 & U_3 \\ \cos t - \sin t & \sin t + \cos t & 1 \\ -2\sin t & 2\cos t & 1 \end{vmatrix} \\ &= e^{2t}(\sin t - \cos t, -\sin t - \cos t, 2),\end{aligned}$$

$$\|\alpha'(t) \times \alpha''(t)\| = e^{2t} \sqrt{6},$$

$$\begin{aligned}\alpha'(t) \times \alpha''(t) \cdot \alpha'''(t) &= e^{3t} \begin{vmatrix} \cos t - \sin t & \sin t + \cos t & 1 \\ -2\sin t & 2\cos t & 1 \\ -2\sin t - 2\cos t & 2\cos t - 2\sin t & 1 \end{vmatrix} \\ &= e^{3t}[(\cos t - \sin t)(2\sin t) - (\sin t + \cos t)(2\cos t) + 4] = 2e^{3t},\end{aligned}$$

$$T = \frac{\alpha'(t)}{\|\alpha'(t)\|} = \frac{e^t(\cos t - \sin t, \sin t + \cos t, 1)}{e^t \sqrt{3}} = \frac{1}{\sqrt{3}}(\cos t - \sin t, \sin t + \cos t, 1),$$

$$\begin{aligned}B &= \frac{\alpha'(t) \times \alpha''(t)}{\|\alpha'(t) \times \alpha''(t)\|} = \frac{e^{2t}(\sin t - \cos t, -\sin t - \cos t, 2)}{e^{2t} \sqrt{6}} \\ &= \frac{1}{\sqrt{6}}(\sin t - \cos t, -\sin t - \cos t, 2),\end{aligned}$$

$$\begin{aligned}N &= B \times T = \frac{1}{3\sqrt{2}} \begin{vmatrix} U_1 & U_2 & U_3 \\ \sin t - \cos t & -\sin t - \cos t & 2 \\ \cos t - \sin t & \sin t + \cos t & 1 \end{vmatrix} \\ &= \frac{1}{3\sqrt{2}}(-3\sin t - 3\cos t, -3\sin t + 3\cos t, 0) = \frac{1}{\sqrt{2}}(-\sin t - \cos t, -\sin t + \cos t, 0),\end{aligned}$$

$$\kappa = \frac{\|\alpha'(t) \times \alpha''(t)\|}{\|\alpha'(t)\|^3} = \frac{e^{2t} \sqrt{6}}{e^{3t} 3\sqrt{3}} = \frac{e^{-t} \sqrt{2}}{3},$$

$$\tau = \frac{\alpha'(t) \times \alpha''(t) \cdot \alpha'''(t)}{\|\alpha'(t) \times \alpha''(t)\|^2} = \frac{2e^{3t}}{6e^{4t}} = \frac{e^{-t}}{3}.$$

b) $s(t) = \int_0^t \|\alpha'(t)\| dt = \int_0^t e^t \sqrt{3} dt = \sqrt{3}(e^t - 1).$

c) Since $\frac{\tau}{\kappa} = \frac{\frac{e^{-t}}{3}}{\frac{e^{-t} \sqrt{2}}{3}} = \frac{1}{\sqrt{2}} \neq 0$ then the curve is a cylindrical helix.

2. Since

$$E_1 = \cos^2 f U_1 + \cos f \sin f U_2 + \sin f U_3$$

$$E_2 = \cos f \sin f U_1 + \sin^2 f U_2 - \cos f U_3$$

$$E_3 = -\sin f U_1 + \cos f U_2,$$

then its attitude matrix is

$$A = \begin{pmatrix} \cos^2 f & \cos f \sin f & \sin f \\ \cos f \sin f & \sin^2 f & -\cos f \\ -\sin f & \cos f & 0 \end{pmatrix} = \begin{pmatrix} \cos^2 f & \frac{1}{2} \sin 2f & \sin f \\ \frac{1}{2} \sin 2f & \sin^2 f & -\cos f \\ -\sin f & \cos f & 0 \end{pmatrix}.$$

Then

$$dA = \begin{pmatrix} -\sin 2f df & \cos 2f df & \cos f df \\ \cos 2f df & \sin 2f df & \sin f df \\ -\cos f df & -\sin f df & 0 \end{pmatrix}.$$

Since

$${}^t A = \begin{pmatrix} \cos^2 f & \frac{1}{2} \sin 2f & -\sin f \\ \frac{1}{2} \sin 2f & \sin^2 f & \cos f \\ \sin f & -\cos f & 0 \end{pmatrix},$$

then we have

$$\begin{aligned} \omega = dA {}^t A &= \begin{pmatrix} -\sin 2f df & \cos 2f df & \cos f df \\ \cos 2f df & \sin 2f df & \sin f df \\ -\cos f df & -\sin f df & 0 \end{pmatrix} \begin{pmatrix} \cos^2 f & \frac{1}{2} \sin 2f & -\sin f \\ \frac{1}{2} \sin 2f & \sin^2 f & \cos f \\ \sin f & -\cos f & 0 \end{pmatrix} \\ &= \begin{pmatrix} 0 & -df & \cos f df \\ df & 0 & \sin f df \\ -\cos f df & -\sin f df & 0 \end{pmatrix} \end{aligned}$$

$$\mathbf{b)} \nabla_{fE_2}(fE_1 + E_3) = f\nabla_{E_2}(fE_1 + E_3)$$

$$= f(E_2[f]E_1 + f\nabla_{E_2}E_1 + \nabla_{E_2}E_3).$$

$$\text{Since } E_2[f] = \cos f \sin f U_1[f] + \sin^2 f U_2[f] - \cos f U_3[f]$$

$$= \frac{1}{2} \sin 2f \frac{\partial f}{\partial x} + \sin^2 f \frac{\partial f}{\partial y} - \cos f \frac{\partial f}{\partial z},$$

$$\nabla_{E_2}E_1 = \sum_j \omega_{1j}(E_2)E_j = \omega_{12}(E_2)E_2 + \omega_{13}(E_2)E_3 = -df(E_2)E_2 + \cos f df(E_2)E_3$$

$$= -E_2[f]E_2 + \cos f E_2[f]E_3 = E_2[f](-E_2 + \cos f E_3),$$

$$\nabla_{E_2}E_3 = \sum_j \omega_{3j}(E_2)E_j = \omega_{31}(E_2)E_1 + \omega_{32}(E_2)E_2 = -\cos f df(E_2)E_1 - \sin f df(E_2)E_2$$

$$= -\cos f E_2[f]E_1 - \sin f E_2[f]E_2 = E_2[f](-\cos f E_1 - \sin f E_2),$$

then we have

$$\nabla_{fE_2}(fE_1 + E_3) = f(E_2[f]E_1 + f\nabla_{E_2}E_1 + \nabla_{E_2}E_3)$$

$$= f(E_2[f]E_1 + fE_2[f](-E_2 + \cos f E_3) + E_2[f](-\cos f E_1 - \sin f E_2))$$

$$= fE_2[f]((1 - \cos f)E_1 - (f + \sin f)E_2 + f \cos f E_3)$$

c) Since $\theta_i = \sum a_{ij}dx_j$ or $\theta = Ad\xi$, then we have

$$\begin{pmatrix} \theta_1 \\ \theta_2 \\ \theta_3 \end{pmatrix} = \begin{pmatrix} \cos^2 f & \frac{1}{2} \sin 2f & \sin f \\ \frac{1}{2} \sin 2f & \sin^2 f & -\cos f \\ -\sin f & \cos f & 0 \end{pmatrix} \begin{pmatrix} dx_1 \\ dx_2 \\ dx_3 \end{pmatrix} \text{ or}$$

$$\begin{pmatrix} \theta_1 \\ \theta_2 \\ \theta_3 \end{pmatrix} = \begin{pmatrix} \cos^2 f dx + \frac{1}{2} \sin 2f dy + \sin f dz \\ \frac{1}{2} \sin 2f dx + \sin^2 f dy - \cos f dz \\ -\sin f dx + \cos f dy \end{pmatrix}.$$

3. Since

$$\begin{aligned} \|F(\mathbf{p}) - F(\mathbf{q})\| &= \|(p_2 - 2, p_3 + 5, p_1 - 1) - (q_2 - 2, q_3 + 5, q_1 - 1)\| \\ &= \|(p_2 - q_2, p_3 - q_3, p_1 - q_1)\| = \|\mathbf{p} - \mathbf{q}\| \end{aligned}$$

then F is an isometry. Since

$$\mathbf{0} = T^{-1}(F(\mathbf{0})) = -\mathbf{a} + F(\mathbf{0}) = -\mathbf{a} + (-2, 5, -1)$$

then T is a translation by $(-2, 5, -1)$. Since

$$\begin{aligned} C(\mathbf{p}) &= (T^{-1}F)(\mathbf{p}) = T^{-1}(F(\mathbf{p})) = F(\mathbf{p}) + (2, -5, 1) \\ &= (p_2 - 2, p_3 + 5, p_1 - 1) + (2, -5, 1) = (p_2, p_3, p_1) \end{aligned}$$

then we have

$$\begin{pmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \\ c_{31} & c_{32} & c_{33} \end{pmatrix} \begin{pmatrix} p_1 \\ p_2 \\ p_3 \end{pmatrix} = \begin{pmatrix} p_2 \\ p_3 \\ p_1 \end{pmatrix} \Rightarrow C = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}.$$